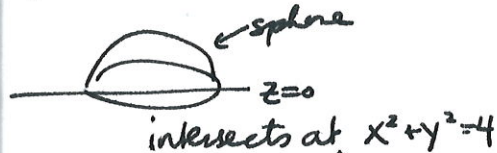


Instructions: Show all work. Answers without work required to obtain the solution will not receive full credit. Some questions may contain multiple parts: be sure to answer all of them. Give exact answers unless specifically asked to estimate.

1. Use Stokes' Theorem to evaluate $\int_S \vec{\nabla} \times \vec{F} \cdot d\vec{S}$ for $\vec{F}(x, y, z) = 2y \cos z \hat{i} + e^x \sin z \hat{j} + xe^y \hat{k}$ where S is the hemisphere $x^2 + y^2 + z^2 = 4, z \geq 0$, oriented upward.

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2y \cos z & e^x \sin z & xe^y \end{vmatrix} =$$



$$(xe^y - e^x \cos z) \hat{i} - (e^y + 2y \sin z) \hat{j} + (e^x \sin z - 2 \cos z) \hat{k} \quad d\vec{S} = \hat{k} \quad z=0$$

$$\left(\frac{\partial}{\partial x} \times \vec{F} \right) \cdot d\vec{S} = e^x \sin z - 2 \cos z \quad \text{at } z=0 \Rightarrow e^x(0) - 2(1) = -2$$

$$\iint -2 \, dA = \int_0^{2\pi} \int_0^2 -2r \, dr \, d\theta = \int_0^{2\pi} -r^2 \Big|_0^2 \, d\theta = -4 \int_0^{2\pi} d\theta =$$

$$\boxed{-8\pi}$$

2. Find the unit tangent vector and the unit normal vector for $\vec{r}(t) = 3t\hat{i} + 4 \sin t \hat{j} + 4 \cos t \hat{k}$.

$$\vec{r}'(t) = 3\hat{i} + 4 \cos t \hat{j} - 4 \sin t \hat{k} \quad \|\vec{r}'(t)\| = \sqrt{3^2 + 16 \cos^2 t + 16 \sin^2 t} = \sqrt{9+16} = \sqrt{25} = 5$$

$$\boxed{T(t) = \frac{3}{5}\hat{i} + \frac{4}{5} \cos t \hat{j} - \frac{4}{5} \sin t \hat{k}}$$

$$T'(t) = 0\hat{i} - \frac{4}{5} \sin t \hat{j} - \frac{4}{5} \cos t \hat{k} \quad \|T'(t)\| = 4/5$$

$$\boxed{N(t) = -\sin t \hat{j} - \cos t \hat{k}}$$

3. Find an equation of the tangent plane to the surface $\vec{r}(u, v) = u^2 \hat{i} + 2u \sin v \hat{j} + u \cos v \hat{k}$ where $u = 1, v = 0$.

$$\vec{r}_u = 2u\hat{i} + 2\sin v \hat{j} + \cos v \hat{k} \Rightarrow 2\hat{i} + 0\hat{j} + 1\hat{k}$$

$$\vec{r}_v = 0\hat{i} + 2u \cos v \hat{j} - u \sin v \hat{k} \Rightarrow 0\hat{i} + 2\hat{j} + 0\hat{k}$$

$$\begin{matrix} (1, 0, 1) \\ \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & 0 & 1 \\ 0 & 2 & 0 \end{vmatrix} = \vec{r}_u \times \vec{r}_v \\ = (0-2)\hat{i} - (2-0)\hat{j} + (4-0)\hat{k} \\ \langle -2, -2, 4 \rangle \end{matrix}$$

$$-2(x-1) - 2(z-1) = 0$$