

$$1. T: \vec{x} \in \mathbb{R}^3 \rightarrow A\vec{x} \in \mathbb{R}^3$$

$$A = \begin{bmatrix} 1 & 4 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 2 \end{bmatrix} \quad A\vec{x} = \begin{bmatrix} 1 & 4 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 + 4x_2 + 0x_3 \\ 0x_1 + 0x_2 - x_3 \\ 0x_1 + 0x_2 + 2x_3 \end{bmatrix} = T$$

Since we can write T as a matrix, it satisfies the first two properties of linear transformations since all matrices have the property that $A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v}$ and $A(c\vec{u}) = c(A\vec{u})$, therefore so does T . Checking $T(0) = 0$ we

see that $\begin{bmatrix} 1 & 4 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ does equal $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$. //

$$2. T: \vec{x} \in \mathbb{R}^3 \rightarrow \vec{b} \in \mathbb{R}^3$$

however since T can't be represented by a matrix, we check the properties by hand.

$$a) T(\vec{u} + \vec{v}) = T(\vec{u}) + T(\vec{v})$$

$$\text{consider } \begin{bmatrix} 4 \\ 1 \\ 2 \end{bmatrix} = \vec{u} \text{ and } \vec{v} = \begin{bmatrix} 0 \\ 3 \\ 1 \end{bmatrix}$$

$$\vec{u} + \vec{v} = \begin{bmatrix} 4 \\ 4 \\ 3 \end{bmatrix} \quad T\left(\begin{bmatrix} 4 \\ 4 \\ 3 \end{bmatrix}\right) = \begin{bmatrix} 3 - 7 \\ 4 \cdot 9 + 5 \\ 0 \end{bmatrix} = \begin{bmatrix} -4 \\ 54 \\ 0 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 4 \\ 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 2 - 4 \\ 16 + 5 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 \\ 21 \\ 0 \end{bmatrix} \quad T\left(\begin{bmatrix} 0 \\ 3 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 - 3 \\ 9 + 5 \\ 0 \end{bmatrix} = \begin{bmatrix} -3 \\ 14 \\ 0 \end{bmatrix}$$

$$\text{but } T(\vec{u}) + T(\vec{v}) = \begin{bmatrix} -4 \\ 35 \\ 0 \end{bmatrix} \text{ not } \begin{bmatrix} -4 \\ 54 \\ 0 \end{bmatrix}$$

Since at least one property fails even once, this is not a linear transformation. //

3. This example is similar to the one variable derivative example, but $\nabla f, \nabla g$ are vectors

3 cont'd.

$$a) \nabla f = \begin{bmatrix} f_x \\ f_y \\ f_z \end{bmatrix} \quad \nabla g = \begin{bmatrix} g_x \\ g_y \\ g_z \end{bmatrix} \quad \nabla f + \nabla g = \begin{bmatrix} f_x + g_x \\ f_y + g_y \\ f_z + g_z \end{bmatrix}$$

$$\nabla(f+g) = \begin{bmatrix} (f+g)_x \\ (f+g)_y \\ (f+g)_z \end{bmatrix} \quad \text{Since these are partial derivative operators w/ the same properties as } \frac{d}{dx} \text{ we can say that}$$

$$\begin{bmatrix} (f+g)_x \\ (f+g)_y \\ (f+g)_z \end{bmatrix} = \begin{bmatrix} f_x + g_x \\ f_y + g_y \\ f_z + g_z \end{bmatrix} \quad \text{Therefore } \nabla(f+g) = \nabla f + \nabla g \checkmark$$

$$b) \nabla(kf) = \begin{bmatrix} (kf)_x \\ (kf)_y \\ (kf)_z \end{bmatrix} \quad \text{by properties of derivatives} = \begin{bmatrix} k f_x \\ k f_y \\ k f_z \end{bmatrix}$$

$$\text{which} = k \begin{bmatrix} f_x \\ f_y \\ f_z \end{bmatrix} = k \nabla f \checkmark$$

$$c) \nabla(0) = \begin{bmatrix} \frac{\partial}{\partial x} [0] \\ \frac{\partial}{\partial y} [0] \\ \frac{\partial}{\partial z} [0] \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \checkmark$$

Since ∇ satisfies all the properties of a linear transformation it is one. //

$$4. A = \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \quad \text{let } \vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \quad \vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \quad \text{w/ } u_1, u_2, v_1, v_2 \in \mathbb{R}$$

$$\vec{u} + \vec{v} = \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \end{bmatrix} \quad c\vec{u} = \begin{bmatrix} cu_1 \\ cu_2 \end{bmatrix}$$

$$a) A(\vec{u} + \vec{v}) = \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \end{bmatrix} = \begin{bmatrix} 2u_1 + 2v_1 + 3u_2 + 3v_2 \\ -u_1 - v_1 + 4u_2 + 4v_2 \end{bmatrix}$$

$$A(\vec{u}) + A(\vec{v}) = \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} + \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 2u_1 + 3u_2 \\ -u_1 + 4u_2 \end{bmatrix} + \begin{bmatrix} 2v_1 + 3v_2 \\ -v_1 + 4v_2 \end{bmatrix} = \begin{bmatrix} 2u_1 + 2v_1 + 3u_2 + 3v_2 \\ -u_1 - v_1 + 4u_2 + 4v_2 \end{bmatrix} \checkmark$$

4 cont'd

$$b) A(c\vec{u}) = \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} cu_1 \\ cu_2 \end{bmatrix} = \begin{bmatrix} 2cu_1 + 3cu_2 \\ -cu_1 + 4cu_2 \end{bmatrix}$$

$$c(A\vec{u}) = c \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = c \begin{bmatrix} 2u_1 + 3u_2 \\ -u_1 + 4u_2 \end{bmatrix} = \begin{bmatrix} c(2u_1 + 3u_2) \\ c(-u_1 + 4u_2) \end{bmatrix}$$

which by the distributive property gives us $A(c\vec{u})$. ✓

$$c) \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \checkmark$$

therefore, A is a linear transformation. Since A is a matrix and must satisfy properties of matrices, this was to be expected. ✓

$$5. A = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \quad \text{let } u = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}, v = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \quad \text{w/ } u_1, u_2, v_1, v_2 \in \mathbb{R}$$

$$a) A(\vec{u} + \vec{v}) = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \end{bmatrix} = \begin{bmatrix} \cos \theta (u_1 + v_1) + \sin \theta (u_2 + v_2) \\ -\sin \theta (u_1 + v_1) + \cos \theta (u_2 + v_2) \end{bmatrix}$$

$$A\vec{u} + Av = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} + \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} =$$

$$\begin{bmatrix} \cos \theta \cdot u_1 + \sin \theta \cdot u_2 \\ -\sin \theta \cdot u_1 + \cos \theta \cdot u_2 \end{bmatrix} + \begin{bmatrix} \cos \theta \cdot v_1 + \sin \theta \cdot v_2 \\ -\sin \theta \cdot v_1 + \cos \theta \cdot v_2 \end{bmatrix} =$$

$$\begin{bmatrix} \cos \theta \cdot u_1 + \sin \theta \cdot u_2 + \cos \theta \cdot v_1 + \sin \theta \cdot v_2 \\ -\sin \theta \cdot u_1 + \cos \theta \cdot u_2 - \sin \theta \cdot v_1 + \cos \theta \cdot v_2 \end{bmatrix}$$

Collecting $\sin \theta$ & $\cos \theta$ terms in each component gives

$$\begin{bmatrix} \cos \theta (u_1 + v_1) + \sin \theta (u_2 + v_2) \\ -\sin \theta (u_1 + v_1) + \cos \theta (u_2 + v_2) \end{bmatrix} \quad \text{which was our previous result. } \checkmark$$

$$b) A(c\vec{u}) = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} cu_1 \\ cu_2 \end{bmatrix} = \begin{bmatrix} cu_1 \cos \theta + cu_2 \sin \theta \\ -cu_1 \sin \theta + cu_2 \cos \theta \end{bmatrix} = c \begin{bmatrix} u_1 \cos \theta + u_2 \sin \theta \\ -u_1 \sin \theta + u_2 \cos \theta \end{bmatrix}$$

$$c) A\vec{u} = c \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = c \begin{bmatrix} \cos \theta \cdot u_1 + \sin \theta \cdot u_2 \\ -\sin \theta \cdot u_1 + \cos \theta \cdot u_2 \end{bmatrix} \quad \text{which is the same as above.}$$

$$c) \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \checkmark \quad //$$

6. consider the integration operator $\int_0^x \int_0^y f(u,v) du dv$ for generic functions $f(u,v)$ and $g(u,v)$.

a) $\int_0^x \int_0^y (f(u,v) + g(u,v)) du dv = \int_0^x \int_0^y f(u,v) du dv + \int_0^x \int_0^y g(u,v) du dv$

by properties of the integration operator.

b) $\int_0^x \int_0^y kf(u,v) du dv = k \int_0^x \int_0^y f(u,v) du dv$ by properties of integration.

c) $\int_0^x \int_0^y 0 du dv = 0$ by properties of definite integrals.

7. $A = \begin{bmatrix} -2 & 0 & 1 \\ 3 & -1 & 5 \\ 2 & -4 & 0 \end{bmatrix}$ since A is a matrix it satisfies the matrix properties $A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v}$,

the first of our properties of a linear transformation, and also

$A(c\vec{u}) = c(A\vec{u})$, the second property. It's also clear that

$$\begin{bmatrix} -2 & 0 & 1 \\ 3 & -1 & 5 \\ 2 & -4 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} //$$

8. $T: \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2 \rightarrow \begin{bmatrix} r \\ \theta \end{bmatrix}$ in \mathbb{R}^2

this transformation is not linear since

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} \sqrt{2} \\ \frac{\pi}{4} \end{bmatrix} \quad \text{but} \quad 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \not\rightarrow \begin{bmatrix} 2\sqrt{2} \\ \frac{\pi}{2} \end{bmatrix}$$

rather, it maps $\begin{bmatrix} 2 \\ 2 \end{bmatrix} \rightarrow \begin{bmatrix} 2\sqrt{2} \\ \frac{\pi}{4} \end{bmatrix}$ therefore the second property (at least) fails. //